

Info card

Inductive Kplus sensors



i This info card serves as a supplement to the main position sensors catalogue and to the individual data sheets. For further information and contact addresses please visit our homepage at www.ifm.com

Intended use

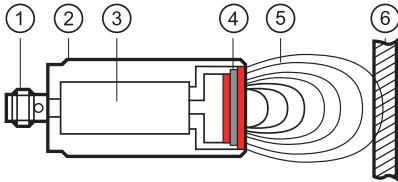
While in use the products are exposed to influences which may have an effect on function, life, quality and reliability of the product.

It is the customer's responsibility to ensure that the products are suitable for the intended application. This applies in particular to applications in hazardous areas and with adverse environmental influence such as pressure, chemicals, temperature fluctuations, moisture and radiation as well as mechanical stress, especially if the products are not installed properly.

Using the products in applications where the safety of people depends on the function of the product is not permitted. Non-compliance may result in death or serious injuries.

Operating principle of an inductive Kplus sensor

Same sensing range on all metals (correction factor = 1). A transmitting and receiving coil system on a PCB constitutes a transformer. Electrically conductive materials in the near field affect the coupling factor of the transformer. The change of the coupling factor is converted into a switched output. By not using a ferrite core, the inductive Kplus sensors are less sensitive to interference caused by strong magnetic fields.



- ① Connection

② Housing

③ Evaluation circuit
- ④ PCB with transmitting and receiving coil

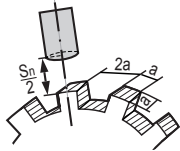
⑤ Alternating electromagnetic field = active zone

⑥ Target = electrically conductive material

Glossary of important terms

Active zone	Area above the sensing face in which the sensor reacts to the approach of the target.	
Output function	Normally open:	Object within the active zone > output switched.
	Normally closed:	Object within the active zone > output blocked.
	Positive switching:	positive output signal (to L-).
	Negative switching:	negative output signal (to L+).
Rated insulation voltage	DC units with protection class II: 250 V DC units with protection class III: 60 V DC	
Rated short-circuit current	For short-circuit-proof units: 100 A	
Rated impulse withstand voltage	DC units with protection class II: 4 kV (Δ overvoltage category III) DC units with protection class III: 60 V DC: 0.8 kV (Δ overvoltage category II)	
Power-on delay time	The time the sensor needs to be ready for operation after application of the operating voltage (in the millisecond range).	
Operating voltage	The voltage range in which the sensor functions safely. A stabilised and smoothed direct voltage should be used! Take into account residual ripple!	
Utilisation category	DC units: DC-13 (control of solenoids)	

Hysteresis	Difference between the switch-on and the switch-off point.
Short-circuit protection	ifm sensors are protected against excessive current by means of a pulsed short-circuit protection. The inrush current of incandescent lamps, electronic relays and low resistance loads may cause this protection to cut in and turn the sensor off!
Standard target	Square steel plate (e.g. S235JR) of a thickness of 1 mm with a side length (a) equal to the diameter of the sensing face or 3 x S _N , depending on which value is the highest.
Product standard	IEC 60947-5-2
Repeatability	Difference between any two S _r measurements. Max. 10 % of S _r .
Switch point drift	Shift in the switch point owing to changes in the ambient temperature.
Switching frequency	Damping with standard target (a x a) at half S _N . The ratio damped to undamped (mark to space) = 1 : 2.



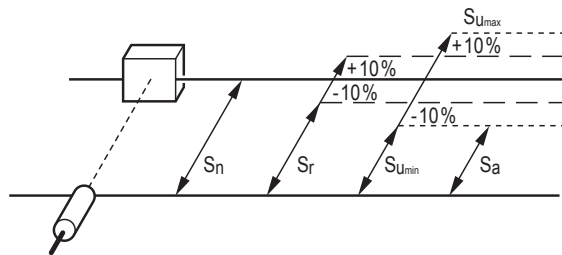
Protection	IPxy	According to IEC 60529
	IP68	Test condition: 1 m water depth for 7 days
	IP69k	To ISO 20653 (replacement for DIN 40050-9)
Current consumption	Current for the internal supply of 3-wire DC units.	
Transport and storage conditions	Unless otherwise indicated in the data sheet, the following applies: Transport and storage temperature: Min. = - 40 °C. Max. = max. ambient temperature according to the data sheet. The relative air humidity (RH) must not exceed 50 % at +70 °C. At lower temperatures, a higher air humidity is permissible. Shelf life: 5 years. Transport and storage height: no restrictions.	
Degree of soiling	Inductive proximity sensors are designed for degree of soiling 3.	
Maintenance, repair and disposal	If used correctly, no maintenance and repair measures are necessary. Only the manufacturer is allowed to repair the unit. After use dispose of the unit in an environmentally friendly way in accordance with the applicable national regulations.	

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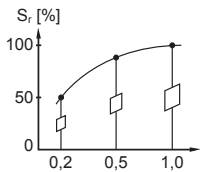


Sensing range (referred to the standard target)



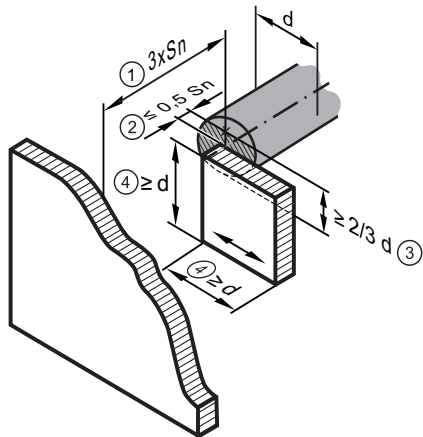
- Nominal sensing range S_n = characteristic value of the unit
- Real sensing range S_r = individual deviation at room temperature between 90 % and 110 % of S_n
- Useful sensing range S_u = switch point drift between 90 % ($S_{u\min}$ = S_a) and 110 % ($S_{u\max}$) of S_r
- Assured sensing range = operating distance S_a = reliably switched between 0 % and 81 % of S_n
- Safe switch-off distance = $S_{u\max}$ + max. hysteresis = 143 % of S_n

Influence of the target size



x axis: ratio actual target / standard target

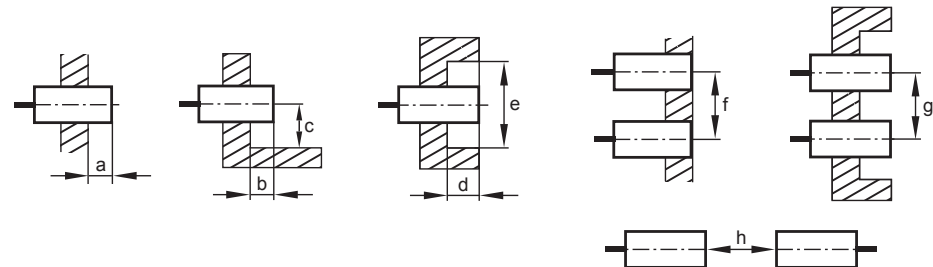
Recommended detection conditions



- ① Distance to the background
- ② Recommended target distance
- ③ Recommended degree of coverage of the sensing face
- ④ Recommended target size

Tips on flush and non-flush mounting in metal

Installation instructions cylindrical designs



		S_n	a	b	c	d	e	f	g	h
M8	b	1,5	-	-	7	-	-	16		8x S_n
		3	-	-	7	-	-	16		
	nb	4	8	8	12	8	32	-	32	
		6	8	12	12	12	32	-	32	
M12	b	3	-	-	8	-	-	24	-	
		4	-	-	8	-	-	24	-	
	nb	8	10	10	18	16	36	-	48	
		10	12	20	18	20	48	-	48	
M18	b	5	-	-	11	-	-	36	-	
		8	-	-	11	-	-	36	-	
	nb	12	15	15	27	24	54	-	72	
		15	18	30	27	30	72	-	72	
M30	b	10	-	-	17	-	-	60	-	
		15	-	-	17	-	-	60	-	
	nb	22	22,5	22,5	45	37	90	-	150	
		30	30	37	45	37	150	-	150	

Installation instructions rectangular designs → see enclosed operating instructions or www.ifm.com

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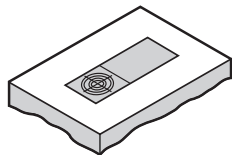
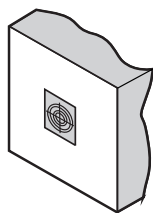
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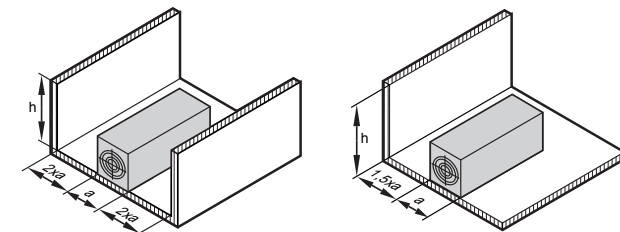


Installation instructions rectangular designs

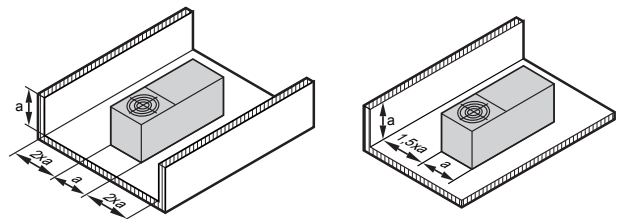
Flush:



Non-flush:



$h = \text{any}$



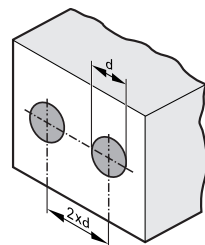
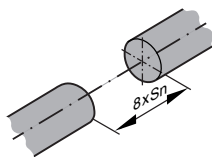
i If the required clear space is not observed for non-flush units, the sensor is predamped. This may lead to permanent switching.

i Possibly deviating installation instructions for rectangular units with increased sensing range
→ Notes on mounting and operation.

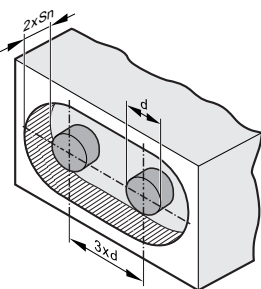
Minimum clearance for installing units of the same type (side-by-side installation)

Applies to cylindrical and rectangular sensors.

Flush:

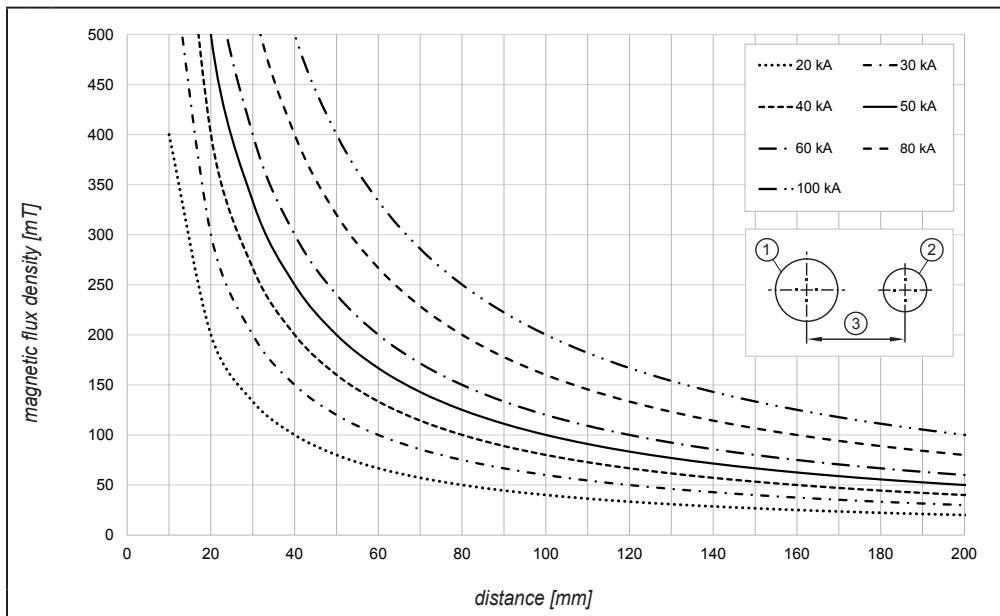


Non-flush:



i The minimum distance between units may only be disregarded for units with different oscillator frequencies or different sensing principles.

Magnetic flux density depending on distance and current



① live wire

② sensor

③ distance

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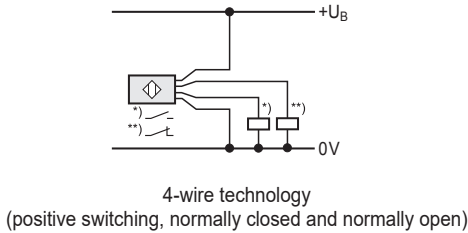
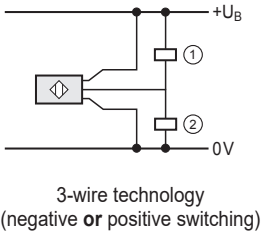


Electrical connection

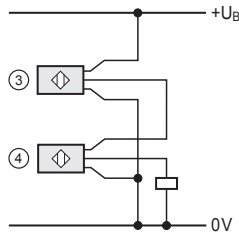
! The unit must be connected by a qualified electrician.

- ① Negative switching
- ② Positive switching
- ③ Sensor 1
- ④ Sensor n

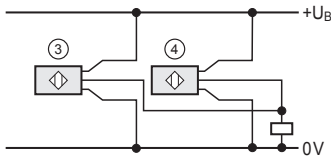
Connection systems



Series connection (AND)



Parallel connection (OR)



Series connection of 3-wire units
Max. 4 units. Power-on delay times, voltage drops and current consumption add up. $U_{B \min}$ (sensor) and $U_{HIGH \min}$ (load) must remain unchanged.

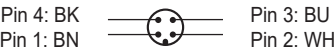
Parallel connection 3-wire units
The current consumption of all non-switched units adds up. The units can be used in combination with mechanical switches.

Configuration of cables and connectors

Colours: BK: black, BN brown, BU: blue, WH: white
Standard configuration for 3-wire DC:

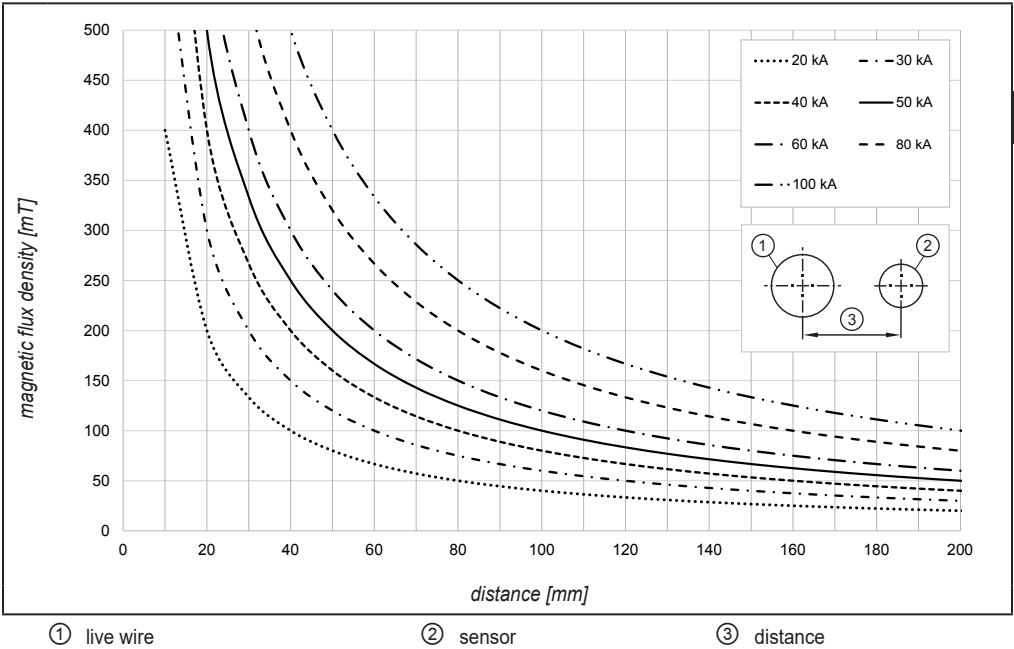
		Cable	US-100 plug
L+		BN	Pin 1 / BN
L-		BU	Pin 3 / BU
Output		BK	Pin 2 / WH Pin 4 / BK

Pin configuration of the US-100 connectors (view onto the plug at the unit)



Please refer to the wiring diagrams in our main catalogue for position sensors for the cable and the pin configuration as well as the unit data of special versions.

Magnetic flux density depending on distance and current



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